

Beyond Bounds: Quantifying the Probability of Counterfactual Fairness

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Our Question & Contributions

How likely is a predictor $\hat{Y}$ to be counterfactually fair?

We estimate the **probability** that a predictor $\hat{Y}$ is counterfactually fair under a stated prior, given $P(\mathbf{V})$ and a causal graph $\mathcal{G}$.

- We show that the compatible parameter space is a **convex polytope**.
- We characterize the **counterfactually fair region** within the space.
- We estimate the target with **Hit-and-Run sampling**, complementing prior-free worst-case bounds.

Counterfactual Fairness

Definitions.

- Counterfactual Effect

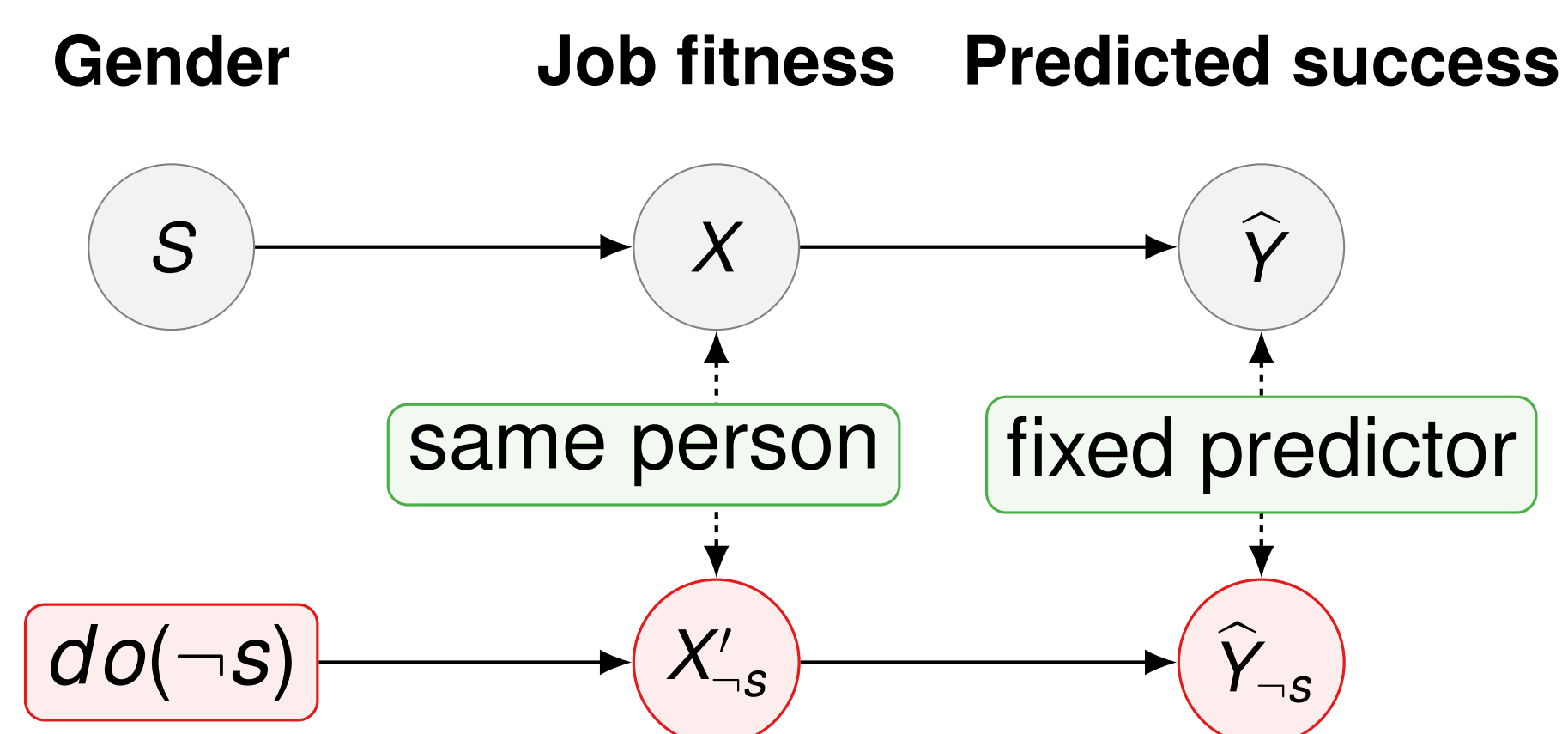
$$CE(s, \neg s \mid \mathbf{x}; \hat{Y}) = P(\hat{Y}_{\neg s} \mid \mathbf{x}, s) - P(\hat{Y} \mid \mathbf{x}, s).$$

- τ -Counterfactual Fairness

$$\hat{Y} \text{ is } \tau\text{-counterfactually fair} \iff \max_{s, \mathbf{x}, \hat{Y}: P(\mathbf{x}, s) > 0} |CE(s, \neg s \mid \mathbf{x}; \hat{Y})| \leq \tau.$$

Example.

- $\hat{Y}$ is counterfactually fair with respect to gender (S) if its prediction remains unchanged under a counterfactual change in gender.



Fairness Probability over Parameter Space

We adopt canonical SCMs to represent candidate causal mechanisms and map models compatible with $\langle P(\mathbf{V}), \mathcal{G} \rangle$ to a d -dimensional space.

Canonical SCM.¹

- A Structural Causal Model (SCM) is a 4-tuple $\mathcal{M} = \langle \mathbf{U}, \mathbf{V}, \mathbf{F}, P(\mathbf{U}) \rangle$:
 - $\mathbf{U}$: exogenous, $\mathbf{V}$: endogenous, $\mathbf{F}$: mechanisms
- A canonical SCM (C-SCM) is defined on finite $\mathbf{V}$, where $\mathbf{U}$ indexes deterministic response functions $\mathbf{F}$.
 - C-SCMs can represent all counterfactual distributions.

Parameterizing C-SCMs.

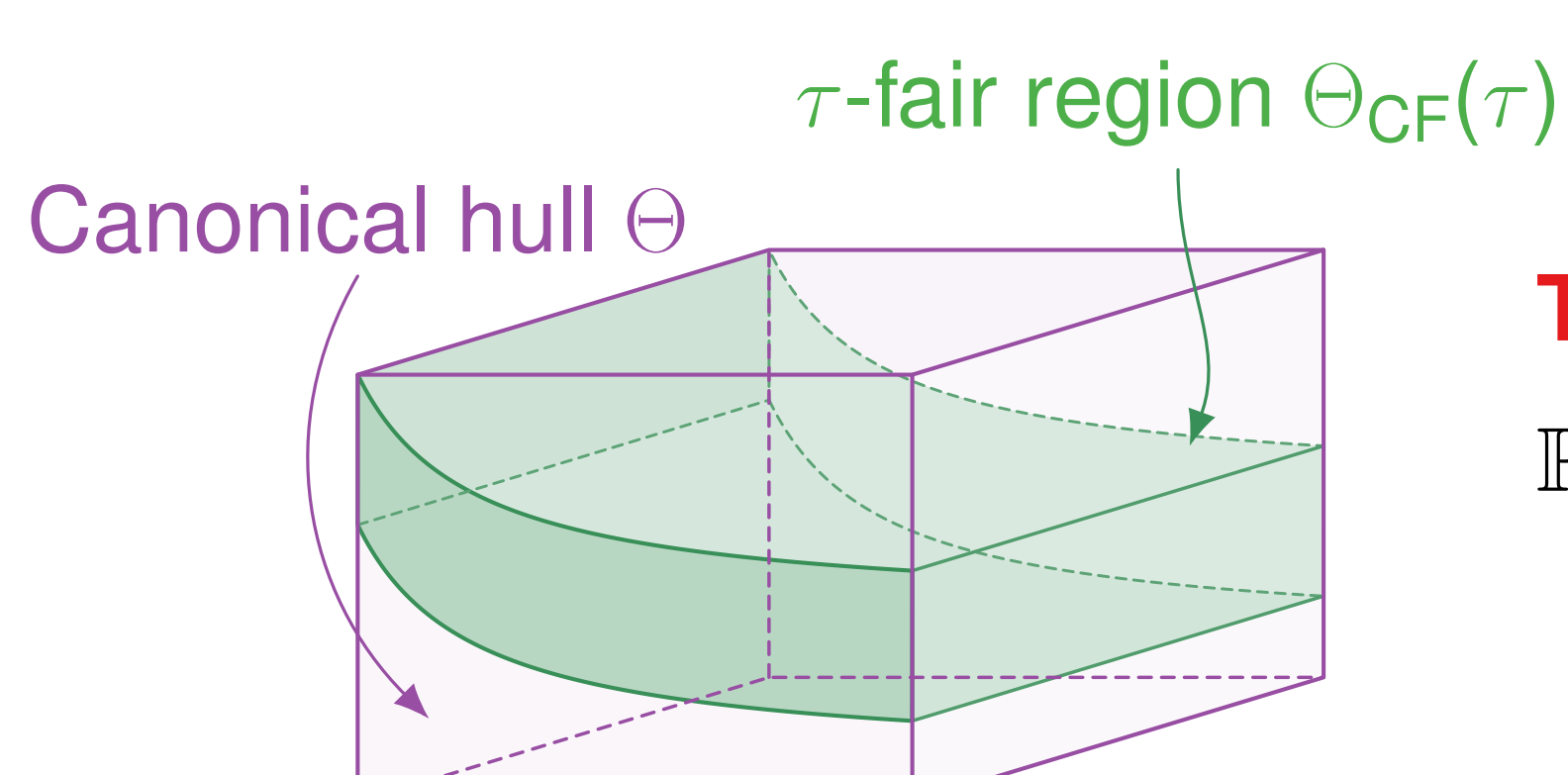
Compatible C-SCMs with the same $\langle P(\mathbf{V}), \mathcal{G} \rangle$ differ only in $P(\mathbf{U})$

- Represent exogenous $P(\mathbf{U})$ by maximal C-component $\{\mathbf{C}_1, \dots, \mathbf{C}_n\}$:

$$\theta_{\mathcal{M}} = [P_{\mathcal{M}}(\mathbf{u}_{\mathbf{C}_1}), \dots, P_{\mathcal{M}}(\mathbf{u}_{\mathbf{C}_n})]^T \in \mathbb{R}^d$$

Parameter Space.

- **Canonical hull.** Θ is the set of $\theta_{\mathcal{M}}$ compatible with $\langle P(\mathbf{V}), \mathcal{G} \rangle$.
- **Fair region.** $\Theta_{CF}(\tau)$ is the set of all $\theta_{\mathcal{M}}$ such that $\hat{Y}$ is τ -CF.



Target Estimand.

$$\mathbb{P}_{\Theta}(\hat{Y} \text{ is } \tau\text{-CF}) = \mathbb{P}_{\Theta}(\theta \in \Theta_{CF}(\tau))$$

Estimating Fairness Probability

Three-step strategy: 1. **Characterize** the canonical hull. 2. **Reduce** to fairness-relevant dimensions. 3. **Sample** by Hit-and-Run.

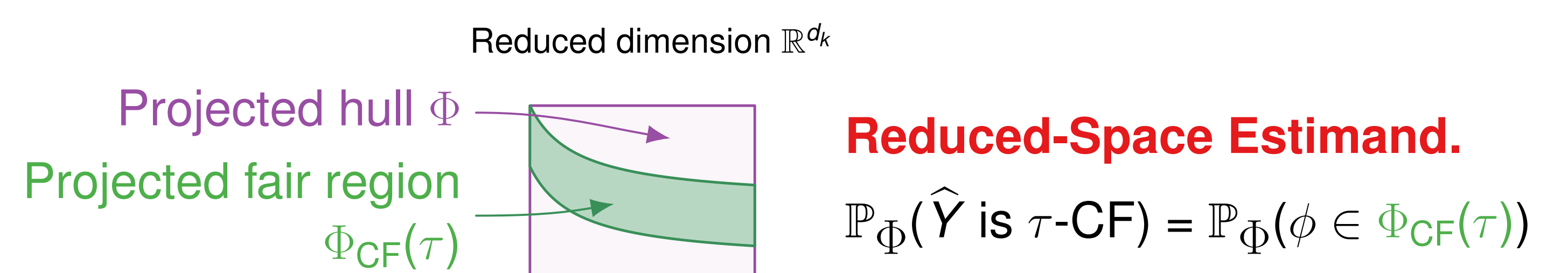
① Characterizing the Canonical Hull

- A canonical hull is a **convex polytope**. $A_1 \cdot \theta = b_1, A_2 \cdot \theta \leq b_2$

② Dimension Reduction

- Evaluate the target in **fairness-relevant dimensions**.
- Retain only C-components intersecting **descendants of S** :

$$\phi_{\mathcal{M}} = \pi(\theta_{\mathcal{M}}) \in \mathbb{R}^{d_k}, \quad \pi : \text{coordinate projection}$$



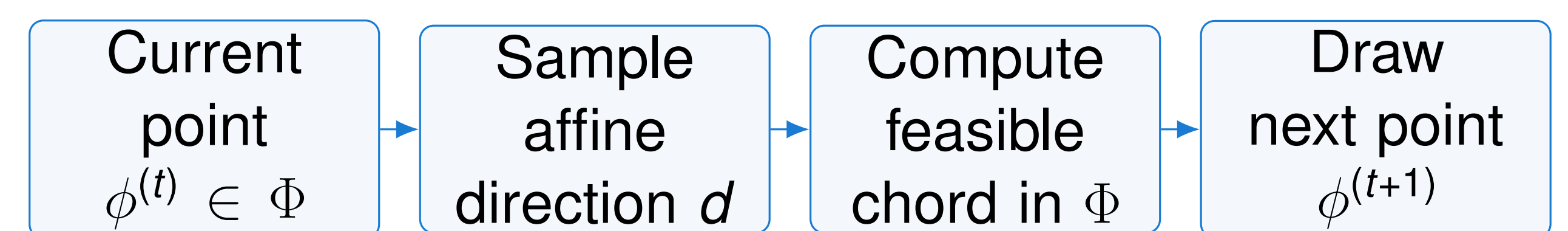
Reduced-Space Estimand.

$$\mathbb{P}_{\Phi}(\hat{Y} \text{ is } \tau\text{-CF}) = \mathbb{P}_{\Phi}(\phi \in \Phi_{CF}(\tau))$$

The same fairness event is evaluated in a lower dimension.
A full-space prior induces $\mathbb{P}_{\Phi} = \pi_{\#} \mathbb{P}_{\Theta}$.

③ Hit-and-Run Sampling

- The target estimand is analytically intractable.
- Since the projected hull Φ remains a **convex polytope**, we employ the Hit-and-Run algorithm to estimate the probability.
 - Given a declared density on Φ , initialize at $\phi^{(0)} \in \Phi$ and repeat:

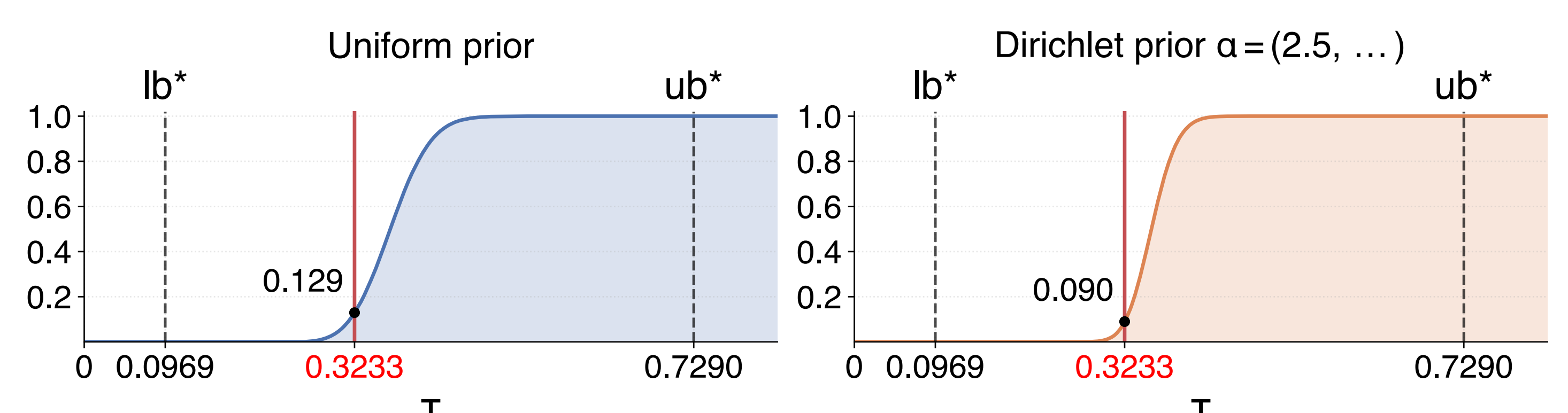


- For retained draws $\phi^{(1)}, \dots, \phi^{(T)}$,

$$\hat{\mathbb{P}}_{\Phi}(\hat{Y} \text{ is } \tau\text{-counterfactually fair}) = \frac{1}{T} \sum_{t=1}^T \mathbb{I}\{\phi^{(t)} \in \Phi_{CF}(\tau)\}.$$

Simulation Studies

We evaluate the synthetic dataset $\mathcal{D}_1$ using 10^5 retained samples under uniform and joint Dirichlet ($\alpha = 2.5$) priors.



- For both priors, the transition region $0 < \hat{\mathbb{P}} < 1$ lies within $[lb^*, ub^*]$ and contains the ground-truth max $|CE|$ value (red lines).
- The probability curves compare how fair-model mass accumulates under the two priors.
- Our method quantifies the probability that $\hat{Y}$ is τ -counterfactually fair, providing actionable information for decision-makers.

¹ Zhang, J., Tian, J., and Bareinboim, E. (2022). *Partial Counterfactual Identification from Observational and Experimental Data*. ICML.